

HANNA JIAMEI ZHANG

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EDUCATION

- Sept 2021 – **Masters of Computer Science (M.Sc.)**, *University of Toronto*,
April 2023 with a Collaborative Specialization in Robotics GPA: 4.00/4.
- Sept 2016 – **Bachelors of Applied Science (B.A.Sc.) with Honours**, *University of Toronto*,
April 2021 *Engineering Science*, Robotics Major, with a Bioengineering Minor and Business Certificate.
Final Year GPA: 4.00/4, Overall GPA: 3.44/4
- Sept 2012 – **IB International Bacclaireate and OSSD (Ontario Secondary School Diploma)**, *Victoria*
June 2016 *Park Collegiate Institute*.

RESEARCH & WORK EXPERIENCE

- May 2023– **Graduate Technology Intern**, WALT DISNEY IMAGINEERING – DISNEY RESEARCH, Los Angeles, CA, USA.
Present
- Worked on first prototype, base operating software, and system integration of a novel acrobatic robot prototype.
 - Implemented methods for motion planning and sensor fusion (motion capture and on-board IMU data streams) in Python.
 - Interfaced with Disney Research Team in Zurich to implement real-time control through reinforcement learning using Isaac Gym and Python.
- April 2020 – **Professor Jessica Burgner-Kahrs**, CONTINUUM ROBOTICS LAB (CRL), University of Toronto
April 2023 – Mississauga, ON, Canada.
Masters Thesis: Distance-Geometric Inverse Kinematics for Tendon-Driven Continuum Robots
Undergraduate Thesis: Teleoperation of a dual-arm continuum robot for single-port surgery with assistive/task-based autonomous control
- Designed and tested a novel distance-based model of continuum robots compatible with state-of-art convex optimization solving techniques.
 - Developed C++ 3D simulator (VTK) and GUI in Qt as well as implemented and tested novel task-priority control for a real dual-arm continuum robot setup.
 - Published and presented both works in reputable journals and conferences.
- June 2019 – **Research & Development Team: Automation Engineering Intern**, INKBOX TATTOOS INC.,
June 2020 Toronto, ON, Canada.
- Developed and tested customized automated measurement, manufacturing, and production line solutions, developed SOP documentation.
 - Ideated and executed on quantifiable methods (computer vision and hardware-based) for measuring production performance/manufacturing, automatic inspection/quality control, and conducted in-vitro/vivo experiments to test validity of solutions.
 - Named inventor on patent for novel semi-permanent tattoo technology.
- May – Aug 2018 **Professor Milos Popovic**, REHABILITATION ENGINEERING LAB (REL), University Health Network – University of Toronto, ON, Canada.
Closed-loop Control of Neuroprosthesis Using Stretch Sensors In a Novel Wearable Configuration

- Developed a state-of-the art wearable stretch sensing sleeve and state-based controller (LabVIEW) to enable more effective rehabilitation in patients with spinal cord injury.
- May – Aug 2017 **Professor Adrian Koh Soo Jin**, DEPARTMENT OF MECHANICAL ENGINEERING, ENGINEERING SCIENCE, National University of Singapore (NUS), Singapore.
 - Designed and tested an antagonistic system comprised of dielectric elastomer artificial muscles based on MATLAB simulation and experimental testing.
- Sept 2015 – Sept 2018 **LEGO Robotics Teaching Lead Instructor/Curriculum Developer**, HOLLAND BLOORVIEW KIDS REHABILITATION HOSPITAL, Toronto, ON, Canada.
 - Developed the basis of this curriculum teaching robot design, sensors, programming autonomous control algorithms, and real-world applications using the EV3 LEGO Mindstorms system. 200+ instructing hours and 75+ hours training volunteers.
- July – Aug 2016 **Professor Kullervo Hynynen**, FOCUSED ULTRASOUND GROUP, Sunnybrook Research Institute, Toronto, ON, Canada
 - Term 1: Biomedical Electronics Design & Testing*
 - Term 2: Effects of Multiple Focused Ultrasound Treatments on Neurogenesis.*

PUBLICATIONS AND PROCEEDINGS

- May 2024 **CIDGIKc: Distance-Geometric Inverse Kinematics for Continuum Robots [PUBLISHED]** Zhang, Hanna et. al., IEEE ROBOTICS AND AUTOMATION LETTERS (RA-L), IEEE INTERNATIONAL CONFERENCE ON ROBOTICS AND AUTOMATION (ICRA) 2024, Yokohama, Japan.
- Sept 2021 **Cooperative Control of Dual-Arm Concentric Tube Continuum Robots [PUBLISHED]** Zhang, Hanna et. al., MARSS 2022 INTERNATIONAL CONFERENCE ON MANIPULATION, AUTOMATION AND ROBOTICS AT SMALL SCALES, Nominated for MARSS 2022 Best Robotics Paper Award, Toronto, Canada.
- Dec 2019 **Semi-permanent tattoos, patent for novel application technology, semi-permanent ink, and manufacturing process, Named Inventor**, INKBOX TATTOOS INC., Toronto, Canada.

AWARDS & DISTINCTIONS

- May 2022 **Ontario Graduate Scholarship (OGS)**, DEPARTMENT OF COMPUTER SCIENCE, UNIVERSITY OF TORONTO, \$15,000 CAD, A prestigious and limited number of merit-based scholarships are awarded to Ontario's best graduate students in all disciplines of academic study.
- June 2021 **Loumankis Family Engineering Graduating Student Scholarship**, COUNCIL OF THE FACULTY OF APPLIED SCIENCE AND ENGINEERING, UNIVERSITY OF TORONTO, \$2,500 CAD, Awarded to 2 graduating undergraduate engineering students for demonstrating outstanding leadership.
- June 2021 **Spirit of EngSci Student Award**, UNIVERSITY OF TORONTO – DIVISION OF ENGINEERING SCIENCE, Presented to graduating students for exemplary non-academic contributions within the University community.
- May 2020 **The Natural Sciences and Engineering Research Council (NSERC) Undergraduate Student Research Award (USRA)**, UNIVERSITY OF TORONTO, \$5,625 CAD, This program supports more than 3,000 students across Canada annually and is administered jointly by Canada's three research granting agencies.
- Sept 2018 **Engineering Society Award Scholarship**, UNIVERSITY OF TORONTO, \$4,448 CAD, Awarded to undergraduate students in the Faculty on the basis of financial need, academic ability, and extra-curricular involvement within the undergraduate engineering community.
- May 2018 **Johannes Michael Holmboe Undergraduate Summer Research Fellowships**, UNIVERSITY OF TORONTO, \$4,620 CAD, One or more fellowship(s) are available based on academic ability, the responsibility of the applicant in the proposed research project, and financial need.

- April 2017 **University of Toronto Student Exchange Bursary**, \$2,750 CAD, Provides travel funds to students who've procured a travel exchange abroad awarded on the merit of the applicants' proposals, academic standing, and financial need.
- April 2017 **National University of Singapore Grant**, \$2,750 CAD, Provides travel funds to students who've procured a travel exchange with the school.
- Sept 2016 **U of T Dean's Merit Award**, UNIVERSITY OF TORONTO, \$7,500 CAD, Given to students entering first year of any undergraduate program in the Faculty on the basis of academic merit.
- June 2016 **Jim McQueen Excellence in Education Award**, VICTORIA PARK COLLEGIATE INSTITUTE, \$1,500 CAD, Recognizes students in the TDSB for their exceptional involvement and service to their school and/or community life.
- June 2016 **The Yip Engineering, Science, and Technology Scholarship**, VICTORIA PARK COLLEGIATE INSTITUTE, \$1,500 CAD, Awarded to one graduating student entering a STEM degree program based on academic merit.
- Feb 2016 **Schulich Leader Scholarship Nominee**, A coveted Canada-wide undergraduate STEM scholarship, selected as the single nominee from my high school.
- Jan 2016 **Status of Women Award — OSSTF District 12 Toronto**, OSSTF TORONTO, The Status of Women Committee Annual Awards Dinner honours outstanding women and women-identified Teachers, Professional Student Services Personnel and students in the TDSB and District 12.
- Mar 2015, 2014 **FIRST Robotics Dean's List Finalist Award – Nominee (2014) & Recipient (2015)**, FIRST Robotics Canada, The Dean's List Award is presented to students who demonstrate exceptional leadership, technical expertise, and a commitment to promoting robotics as a way to inspire more young people to become involved in the field.
- Dec 2015, 2014, 2013 **FIRST LEGO League Youth Mentor Award**, FIRST LEGO LEAGUE CANADA, FIRST Robotics, This award goes to the coach or mentor whose leadership and guidance is clearly evident.

TEACHING ASSISTANTSHIPS

- Spring 2023 **Data Structures and Algorithms**, First year Engsci core C++ programming course.
- Spring 2023 **Engineering Science Option Seminar**, Third year seminar.
- Winter 2022 **Mathematics for Robotics**, Third year Engsci core robotics major course.
- Spring 2022 **Robotics Final Year Capstone Project**, Final/Fourth year Engsci core robotics major capstone course, Head Teaching Assistant.
- Winter 2021 **Fundamentals of Robotics**, Third year Computer Science robotics course.
- Winter 2021 **Introduction to Computer Science**, First year Engsci core Python programming course.
- Summer 2021 **Robotics Final Year Capstone Project Course Development – Drone Racing Platform Development**, Developed autonomous drone platform and curricula for new course offering..
- All held at University of Toronto Departments of Engineering Science, Computer Science, and Robotics Institute.

LEADERSHIP & CO-CURRICULAR ACTIVITIES (SELECTED)

- Feb – Sept 2020 **Vice Chair Operations**, UNIVERSITY OF TORONTO ENGINEERING ORIENTATION COMMITTEE, University of Toronto, Toronto, Canada.
- Led a team of over 400 volunteers to deliver a week of online and in-person programming for over 1000 incoming first-year engineering students, with a budget over \$130k.
- May – Aug 2020 **Summer Student Fellowship**, TROOST INSTITUTE FOR LEADERSHIP EDUCATION IN ENGINEERING, University of Toronto, Toronto, Canada.
- Worked with other student leaders who were deeply committed and driven to improve their own club or organization, myself participating as Vice Chair Operations from Orientation committee.

- May – Sept 2019 **Head Leader**, UNIVERSITY OF TORONTO ENGINEERING ORIENTATION COMMITTEE, University of Toronto, Toronto, Canada.
- Led group activities for 70 incoming Engineering students to the tight-knit community, campus, people, and student life at U of T.
- Sept 2018 – June 2019 **ILead Student Clubs Liason**, TROOST INSTITUTE FOR LEADERSHIP EDUCATION IN ENGINEERING, University of Toronto, Toronto, Canada.
- Connected with student organizations/leaders and promoted/developed ILead's club-oriented initiatives/programming.
- April 2018 – Jan 2019 **Co-Chair Engineering Science Education Conference**, DEPARTMENT OF ENGINEERING SCIENCE, University of Toronto, Toronto, Canada.
- Planned, coordinated and executed on programming for the annual Engineering Science Education Conference (ESEC) with 500+ students in attendance.
- Sept 2017 – April 2018 **Executive NSight – Engineering Science Mentorship Program**, DIVISION OF ENGINEERING SCIENCE, University of Toronto, Toronto, Canada.
- Facilitated a mentor-ship program as well as ran research/industry talks and resume/cover letter workshops.
- Jun 2017 – April 2018 **Co-Director**, RESEARCH EXPERIENCE PROGRAM (GALBRAITH SOCIETY), University of Toronto, Toronto, Canada.
- Coordinated with professors to create research projects that students could apply to.
- Sept 2017 – April 2021 **Engineering Science Ambassador**, DIVISION OF ENGINEERING SCIENCE, University of Toronto, Toronto, Canada.
- Engaged with prospective and newly admitted EngSci students to discuss the program, share my experience, offer mentorship, and answer questions.

PRESENTATIONS AND INVITED GUEST APPEARANCES

- Nov 2022 **Distance-Geometric Inverse Kinematics for Continuum Robots**, *3MT Talk*, UNIVERSITY OF TORONTO ROBOTICS INSTITUTE 3MT COMPETITION, Toronto, Canada.
- Dec 2021 **The Future is Robotic | U of T Groundbreakers EP3**, *Featured Student*, Toronto, Canada.
- Jun 2021 **Teleoperation of a dual-arm continuum robot for single-port surgery with assistive/task-based autonomous control**, *Poster Presentation*, ENGINEERING RESEARCH DAYS: EMPOWERING INNOVATION 2021, University of Toronto, Toronto, Canada.
- May 2021 **Teleoperation of a dual-arm continuum robot for single-port surgery with assistive/task-based autonomous control**, *Virtual Poster*, THE HAMLYN SYMPOSIUM SYMPOSIUM ON MEDICAL ROBOTICS, The Hamlyn Center at Imperial College London, Virtual.
- Aug 2018 **Control of a Neuroprosthesis Using Wearable Stretch Sensors**, *Poster and Podium Presentation*, UNDERGRADUATE ENGINEERING RESEARCH DAY (UNERD), University of Toronto, Toronto, Canada.

SKILLS & ABILITIES

- Programming** C/C++, PYTHON, LABVIEW, MATLAB, JAVA, VERILOG, L^AT_EX
- Software** SOLIDWORKS, QT, LINUX, ILLUSTRATOR/PHOTOSHOP, ROS, ALTIVUM DESIGNER
- Skills** Rapid Prototyping, Machining, Mechatronics Design/Troubleshooting, Soldering and Circuit/PCB Design, 3D Modelling/Design, Public Speaking, Teaching, Community Engagement, Event Organization/Planning, Leadership
- Languages** English (Native proficiency), Mandarin (Native proficiency), French (Conversational)